Compact, Amplifier Built-In Type With Universal Voltage

Features

- Small and power supply built-in type
- Easy installation with LED indicators on product
- Enables to set the operation mode by VR (Light ON/Dark ON)
- Status and output LED indication
- Built-in IC photo diode for disturbing light and electrical noise

Please read "Caution for your safety" in operation manual before using.

CE



XMS-4, MST-□ is sold separately.

Specifications

• Free power, Relay contact output type

Model		BEN10M-TFR	BEN5M-MFR	BEN3M-PFR	BEN300-DFR		
Sensing t	type	Through-beam	Retroreflective (Standard type)	Retroreflective (Built-in polarizing filter)	Diffuse reflective		
Sensing	distance	10m	0.1 to 5m ^{×1}	0.1 to 3m ^{×1}	300mm ^{*2}		
Sensing target		Opaque materials of Min. Ø16mm	Opaque materials of Min. Ø60mm		Translucent, Opaque materials		
Hysteresis					Max. 20% at ratedsetting distance		
Response time		Max. 20ms					
Power su	ipply	24-240VAC ±10% 50/60Hz, 24-240VDC ±10% (Ripple P-P: Max. 10%)					
Current c	consumption	Max. 4VA					
Light sou	rce	Infrared LED (850nm)		Red LED (660nm)	Infrared LED (940nm)		
Sensitivity adjustment		—	Adjustment VR	·			
Operation	n mode	Selectable Light ON or Da	rk ON by VR				
Control o	output	Relay contact output • Relay contact capacity: 30VDC 3A of resistive load, 250VAC 3A resistive load • Relay contact composition: 1c					
Relay life cycle		Mechanically: Min. 50,000,000 operation, Electrically: Min. 100,000 operation					
Light receiving element		Photo IC					
Indicator		Operation indicator: Red LED, Stability indicator: Green LED (The red lamp on Emitter of transmitted beam type is for power indication)					
Insulation resistance		Min. 20MΩ (at 500VDC megger)					
Insulation type		Double or strong insulation (Mark: , Dielectric voltage between the measured input and the power: 1kV)					
Noise resistance		±1,000V the square wave noise (pulse width: 1µs) by the noise simulator					
Dielectric strength		1000VAC 50/60Hz for 1minute					
Mechanical		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min.) in each X, Y, Z direction for 2 hours					
Vibration	Malfunction 1.5mm amplitude at frequency of 10 to 55Hz (for 1 min.) in each X, Y, Z direction for		for 10 minutes				
Ohaala	Mechanical	500m/s ² (approx. 50G) in each X, Y, Z direction for 3 times					
Shock	Malfunction	100m/s ² (approx. 10G) in each X, Y, Z direction for 3 times					
	Ambient illumination	Sunlight: Max. 11,0001x, Incandescent lamp: Max. 3,0001x (Receiver illumination)					
Environ- ment	Ambient temperature	-20 to 65°C, storage: -25 to 70°C					
ment	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH					
Protectio	n structure	IP50 (IEC standard)					
Material		Case, Case cover: Heat	resistant ABS • Sensi	ng part: PC (with polarizing filter	: PMMA)		
Cable		Ø5mm, 5-wire, Length: 2m (Emitter of through-beam type: Ø5mm, 2-wire, Length: 2m) (AWG22, Core diameter: 0.08mm, Number of cores: 60, Insulator out diameter: Ø1.25mm)					
A	Individual	—	Reflector (MS-2)				
Accessory	Common	VR adjustment driver, Mou	R adjustment driver, Mounting bracket, Bolts/nuts				
Unit weig	ht	Approx. 354g	Approx. 208g		Approx. 195g		

×1: The sensing distance is specified with using the MS-2 reflector and the same as the MS-4 reflector. Sensing distance is the setting range of the reflector. The sensor can detect under 0.1m.

When using reflective tapes, the reflectivity will vary by the size of the tape. Please refer to the "Reflectivity By Reflective Tape Model" table before using the tapes.

%2: It is for Non-glossy white paper (100×100mm).

*The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

DC power. Solid state output type

Model		BEN10M-TDT	BEN5M-MDT	BEN3M-PDT	BEN300-DDT	(A) Photoelec Sensors	
Sensing	type	Through-beam	Retroreflective	Retroreflective (with polarizing filter)	Diffuse reflective	(B) Fiber	
Sensing	distance	10m	0.1 to 5m *1	0.1 to 3m ^{×1}	300mm **2	Optic Sensors	
Sensing target		Opaque materials of Min. Ø16mm	Opaque materials of	Opaque materials of Min. Ø60mm		(C) Door/Area	
Hysteresis		_	Max. 20% at rated setting distance		Sensors		
Respons	e time	Max. 1ms				(D) Proximity Sensors	
Power supply		12-24VDC ±10% (Ripple P-P: Max. 10%)					
Current c	consumption	Max. 50mA				(E)	
Light sou	irce	Infrared LED (850nm)		Red LED (660nm)	Infrared LED (940nm)	Pressure Sensors	
Sensitivity adjustment		Adjustment VR					
Operation	n mode		Selectable Light ON or Dark ON by VR				
Control output		NPN open collector / PNP open collector simultaneous output •Load voltage: Max. 30VDC •Load current: Max. 200mA •Residual voltage - NPN: Max. 1V, PNP: Max. 2.5V					
Protection circuit		Reverse polarity protection, Short-circuit protection					
Light receiving element		Photo IC					
Indicator		Operation indicator: Red, Stability indicator: Green (The red lamp on Emitter of transmitted beam type is for power indication)					
Insulation resistance		Min. 20MΩ (at 500VDC megger)					
Noise res	sistance	±240V the square wave	noise (pulse width: 1µs)	by the noise simulator			
Dielectric	strength	1000VAC 50/60Hz for 1minute					
Vibration		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min.) in each X, Y, Z direction for 2 hours					
Shock		500m/s ² (approx. 50G) in each X, Y, Z direction for 3 times					
E au dana a	Ambient illumination	5 /				(J) Counters	
Environ- ment	· · · ·	e -20 to 65°C, storage: -25 to 70°C					
	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH			(K)		
Protectio	n structure	IP50 (IEC standard)					
Material		Case, Case cover: Heat resistant ABS Sensing part: PC (with polarizing filter: PMMA)					
Cable		Ø5mm, 4-wire, Length: 2m (Emitter of through-beam type: Ø5mm, 2-wire, Length: 2m) (AWG22, Core diameter: 0.08mm, Number of cores: 60, Insulator diameter: Ø1.25mm)					
Accessorv	Individual	<u> </u>	Reflector (MS-2)		<u> </u>	(M)	
AUCESSULY	Common	VR adjustment driver, Mounting bracket, Bolts/nuts			(M) Tacho / Speed / P		
Approval		CE				Meters	
Unit weight		Approx. 342g	Approx. 200g		Approx. 187g	(N)	
※1: The	sensing distance is a	specified with using the M	S-2 reflector and the sa	me as the MS-4 reflector. Sens	ing distance is the setting	Display Units	

×1: The sensing distance is specified with using the MS-2 reflector and the same as the MS-4 reflector. Sensing distance is the setting range of the reflector. The sensor can detect under 0.1m.

When using reflective tapes, the reflectivity will vary by the size of the tape. Please refer to the "IReflectivity By Reflective Tape Model" table before using the tapes.

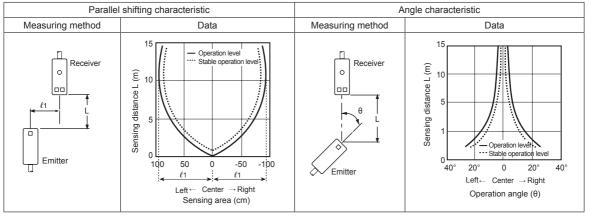
%2: It is for Non-glossy white paper (100×100mm)

*The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

Feature data

O Through-beam type

• BEN10M-TFR • BEN10M-TDT



(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors

& Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

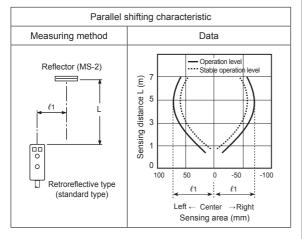
(T) Software



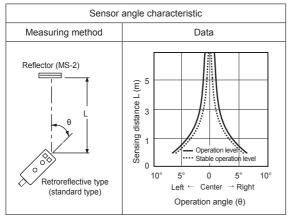
Feature Data

\odot Retroreflective type (Standard type)

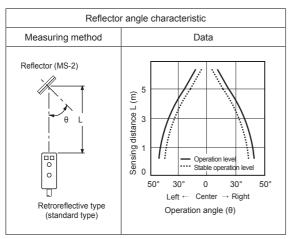
• BEN5M-MFR • BEN5M-MDT



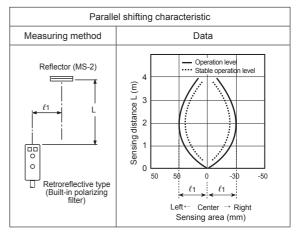
• BEN5M-MFR • BEN5M-MDT



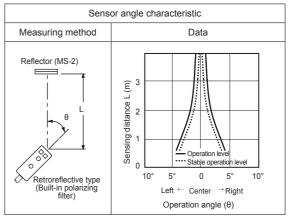
• BEN5M-MFR • BEN5M-MDT



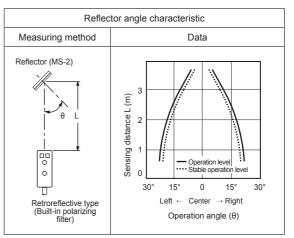
Retroreflective type (Built-in polarizing filter) BEN3M-PFR • BEN3M-PDT



• BEN3M-PFR • BEN3M-PDT

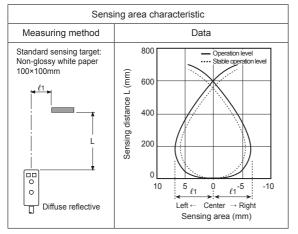


• BEN3M-PFR • BEN3M-PDT



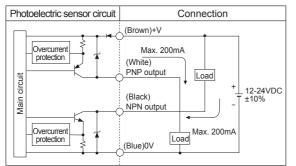
O Diffuse reflective type

• BEN300-DFR • BEN300-DDT

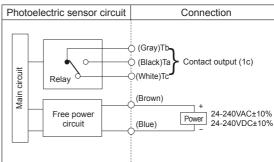


Control Output Diagram

• DC voltage (NPN/PNP synchronous output)

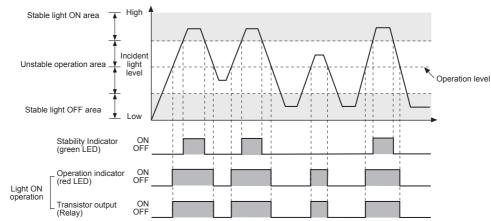


Free power (Relay contact output)



XIn case of product with the output protection device, if terminals of control output are short circuited or overcurrent condition exists, the control output turns OFF due to protection circuit.

Operation Timing Diagram



%The waveforms of "Operation indicator" and "Transistor output" are for Light ON operation. They are opposite operation for Dark ON operation.

Operation Mode

Operation mode	Light ON		(B)		
Receiver operation	Received light		Fiber Optic Sensors		
	Interrupted light				
Operation indicator	ON		(C) Door/Area		
(red LED)	OFF		Sensors		
	ON		(D)		
Transistor output	OFF		Proximity Sensors		
Operation mode		Dark ON	(E) Pressure Sensors		
	Received light	Dark ON	Pressure		
Operation mode Receiver operation	Received light Interrupted light	Dark ON	Pressure Sensors (F) Rotary		
	Ŭ	Dark ON	Pressure Sensors (F)		
Receiver operation	Interrupted light	Dark ON	(F) Rotary Encoders		
Receiver operation Operation indicator	Interrupted light	Dark ON	Pressure Sensors (F) Rotary Encoders		

Temperature Controllers

(A) Photoelectric

(I) SSRs / Power Controllers

(J) Counters

(K) Timers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

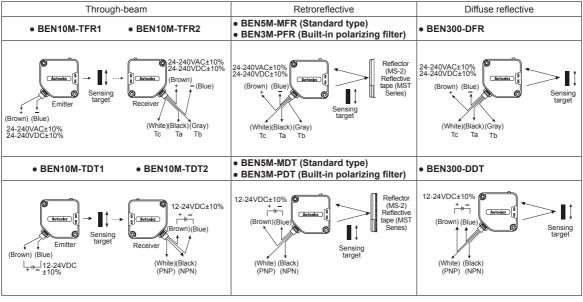
(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software

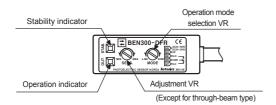
Connections



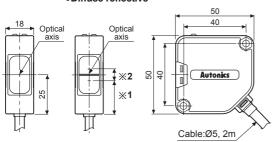
X Unused line must be insulated.

Dimensions

(unit: mm)

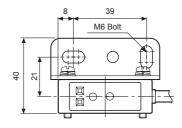


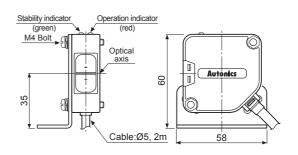
•Through-beam •Retroreflective •Diffuse reflective



%1: Retroreflective: 21.25mm, Diffuse reflective: 20.25mm%2: Retroreflective: 7.5mm, Diffuse reflective: 9.5mm

Connect the bracket



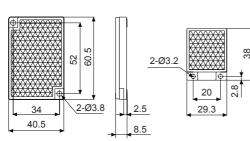


Amplifier Built-in Type With Universal Voltage

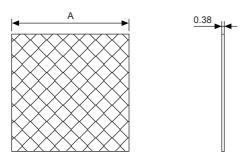
· MS-4 (sold separately)

Reflector

• MS-2

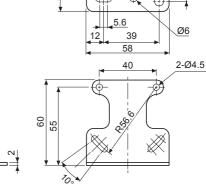


Reflective tape (sold separately)



2

Bracket



21

5.6

M6 Bolt

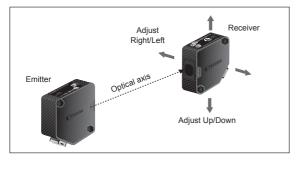
5

	(unit: mm)
	А
MST-50-10	□50
MST-100-5	□100
MST-200-2	□200

Mounting and sensitivity adjustment

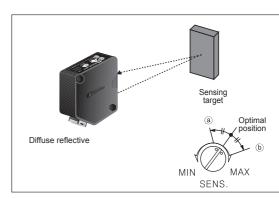
© Through-beam type

- 1. Supply the power to the photoelectric sensor, after setting the emitter and the receiver facing each other.
- 2. Set the receiver in center of position in the middle of the stability range of indicator by adjusting the receiver or the emitter right and left, up and down.
- 3. After the adjustment, check the stability of operation by putting the object at the optical axis.
- ※If the sensing target is translucent body or smaller than Ø16mm, it can be missed by sensor because light penetrate it.



O Diffuse reflective type

- 1. The sensitivity should be adjusted depending on a sensing target or mounting place.
- 2. Set the target at a position to be detected by the beam, then turn the adjustment VR until position (a) where the operation indicator turns ON from min. position of the adjustment VR.
- 3. Take the target out of the sensing area, then turn the adjustment VR until position (6) where the operation indicator turns ON. If the indicator dose not turn ON, max. position is (b).
- 4. Set the adjustment VR at the center of two switching position (a), (b).
- %The sensing distance indicated on specification chart is for 100×100mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.



hotoelectri

(B) Fiber Optic Sensors

(C) Door/Area Sensors

(D) Proximity

(E) Pressure Sensors

Sensor

(F) Rotary Encode

(G) Connectors/ Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

(K) Timers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

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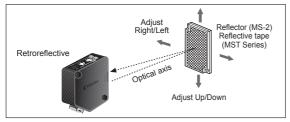
(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software

◎ Retroreflective type

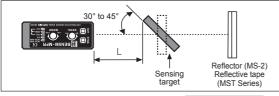
- Supply the power to the photoelectric sensor, after setting the photoelectric sensor and the reflector or reflective tape face to face.
- 2. Set the photoelectric sensor in the position which indicator turns on, by adjusting the reflector or the sensor right and left, up and down.
- 3. Fix both units tightly after checking that the unit detects the target.



%If using more than 2 photoelectric sensors in parallel, the space among them should be more than 30cm.

If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when the target is near to photoelectric sensor. Therefore put enough space between the target and the photoelectric sensor or the surface of the target should be installed at angle of 30° to 45° against optical axis. (When a sensing target with high reflectance near by, photoelectric sensing with the polarizing filter should be used.)

X Sensitivity adjustment: Refer to the diffuse reflective type's.

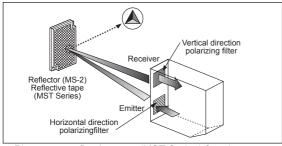


- %If the mounting place is too narrow, please use MS-4 instead of MS-2.
- %Please use reflective tape (MST Series) for where a reflector is not installed.



© Retroreflective type with polarizing filter

The light passed through the polarizing filter of the emitter reaches to the MS-2 reflector or reflective tape converting as horizontal direction. It reaches to the receiver element of polarizing filter converting as vertical by the MS-2 reflector or reflective tape. Therefore, this type can also detect reflective mirror.



%Please use reflective tape (MST Series) for where a reflector is not installed.

Reflectivity By Reflective Tape Model

	Standard	Built-in polarizing filter
MST-50-10 (50×50mm)	90%	70%
MST-100-5 (100×100mm)	130%	90%
MST-200-2 (200×200mm)	140%	120%

%This reflectivity is based on the reflector (MS-2).

※Reflectivity may vary depending on usage environment and installation conditions.

The sensing distance and minimum sensing target size increase as the size of the tape increases. Please check the reflectivity before using reflective

tapes.

%For using reflective tape, installation distance should be min. 20mm.