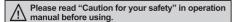
# Multi-Channel (4 Channel / 2 Channel) Modular Type PID Control

## Features

- Multi-channel (4 channel/ 2 channel) simultaneous controlling possible
- High-speed sampling cycle (4 channel: 100ms, 2 channel: 50ms)
- No communication and power supply for expansion modules required by using side connectors: Max. 31 units (124 channels / 62 channels)
- Input channel isolated design (Dielectric strength 1,000 VAC)
- Heating/Cooling simultaneous controlling
- Allows parameter setting by USB port of PC

  - : SCM-US (USB to Serial converter), SCM-38I (RS-232C to RS485 converter), SCM-US48I (USB to RS485 converter)
- Parameter setting by SCM-US without power/wiring
- Easy maintenance via connector type connection
  - : Sensor input connector, control output connector, power/communication connector
- Multi input / Multi range





#### Manual

- Visit our website (www.autonics.com) to download user manual and communication manual.
- User manual describes for specifications and function, and communication manual describes for RS485 communication (Modbus RTU protocol) and parameter address map data.

## ■ Comprehensive Device Management Program (DAQMaster)

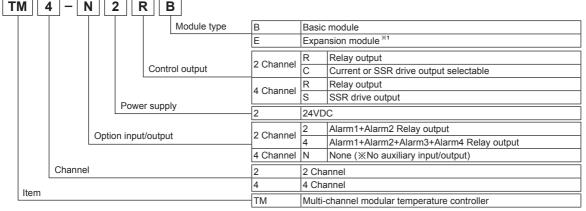
- DAQMaster is comprehensive device management program for convenient management of parameters and multiple device data monitoring.
- Visit our website (www.autonics.com) to download user manual and comprehensive device management program.
- < Computer specification for using software >

Item	Minimum requirements
System	IBM PC compatible computer with Intel Pentium III or above
Operations	Microsoft Windows 98/NT/XP/Vista/7
Memory	256MB+
Hard disk	1GB+ of available hard disk space
VGA	Resolution: 1024×768 or higher
Others	RS-232 serial port (9-pin), USB port

## < DAQMaster screen >



# Ordering Information



Make sure to purchase both expansion module and basic module together because power supply/communication terminals are provided with basic modules only.

H-10 Autonics

## Specifications

Series		TM2- 22RB	TM2- 42RB	TM2- 22RE	TM2- 42RE	TM2- 22CB	TM2- 42CB	TM2- 22CE	TM2- 42CE	TM4- N2RB	TM4- N2RE	TM4- N2SB	TM4- N2SE	
Channel		2 Chani							420L	4 Chan (Each o	nel channel in	sulated-		
Power Sup	ınly	24VDC								Dielec	tric streng	tn 1,000V	/AC)	
	voltage range		10% of rat	ed voltag	10									
Power cons		Max. 5V		eu voitag	je									
Display typ	·			Paramet	er setting	& monito	ring with	evternal d	levices (P	C or PLC	)			
	RTD		Ω, JPt100							0 011 20	,			
Input type	Thermocouple		T, L, N, U	_	`		_	ах. 012 рс	, a wo,					
D: .	RTD Thermocouple**1		.5% or ±1										,	
Display accuracy	CT input	+5% F.S	±5% F.S. ±1digit Max.											
•	Current output		F.S. ±1digit	_						<del> </del>				
Influence of	RTD				the bight	or one) ±1	digit May	(In coop of	of thormos	ounla inn	ut it io ±5'	°C at 100	0°C bolow	
temperature **2	Thermocouple								the highe			C at -100	0°C below.	
	Relay	250VAC	. 3A 1a			<u> </u>				250VA0	3A 1a	Т		
Control		2001710	07114			40) (D.0	.01/00	A 14-		200 17 10	<i>5</i> 67 ( 14	22VDC	±3V30mA	
Control output	SSR					DC 4-2		C 0-20mA	selectabl	e		Max.		
		050)/46	2044-			(load 5	00Ω Max.	)		+				
Option output	Relay Communication		250VAC 3A 1a											
			RS485 Communication output (Modbus RTU)  0.0-50.0A (Primary current measurement range)    CT ratio = 1/1000 —											
Option input	CT input  Digital input	• Conta	ct input: Contact inp	ON Max.	1kΩ, OFF	Min. 100	kΩ	Tall0 = 1/	71000	<del>-</del>				
			w current:	OFF N	Max. 0.1n									
Control method	Heating, cooling Heating&cooling	ON/OF	F control i	mode, P,	PI, PD, P	ID control	mode							
Hysteresis		1 to 100	)°C/°F (0.	1 to 100°0	C/°F) varia	able				1 to 100	0 digit			
Proportiona	al band (P)	0.1 to 9	99.9°C/°F											
Integral tim	ne (I)	0 to 999	99 sec.											
Derivative t	time (D)	0 to 999	99 sec.											
Control per	riod (T)	0.1 to 1	20.0 sec.	(only rela	ay output	and SSR	drive outp	out type)						
Manual res	set value	0.0 to 1	00.0%											
Sampling p	period	50ms (2 chan	nel synch	ronous s	ampling)					100ms (4 chan	nel synch	ronous sa	ampling)	
Dielectric s	trength	1,000V	1,000VAC 50/60Hz for 1 min. (between power source terminal and input terminal)											
Vibration		0.75mm	n amplitud	le at frequ	uency of	5 to 55Hz	(for 1 min	.) in each	X, Y, Z di	rection fo	r 2 hours			
Relay	Mechanical	Min. 10	,000,000	operation	ns									
life cycle	Electrical	Min. 10	0,000 ope	erations (	250VAC 3	BA resista	nce load)							
Insulation r	resistance	100MΩ (at 500VDC megger)												
Noise resis	1	±0.5kV the square wave noise (pulse width: 1us) by the noise simulator												
Environ-	Ambient temperature	-10 to 5	60°C, stora	age: -20 t	o 60°C									
ment	Ambient humidity		5%RH, sto		to 85%R	H								
Accessory			ion conne		onnector (		nodule on	ly)						
Insulation t	уре		insulatior □, Dielec				easuring i	nput part	and the po	ower part	: 1kV)			
Approval		<b>F</b> <sub>0</sub> 3)	us											
Unit weight	ł	Approx.	Approx.	Approx	Approx	. Approx	. Approx	Approx 130g	. Approx.	Approx 174g	. Approx.	Approx.	Approx.	

<sup>%1:</sup> In case of thermocouple K, T, N, J, E at -100°C below and L, U, Platinel II, it is ±2°C ±1digit Max.

Logic Panels H-11

**Autonics** 

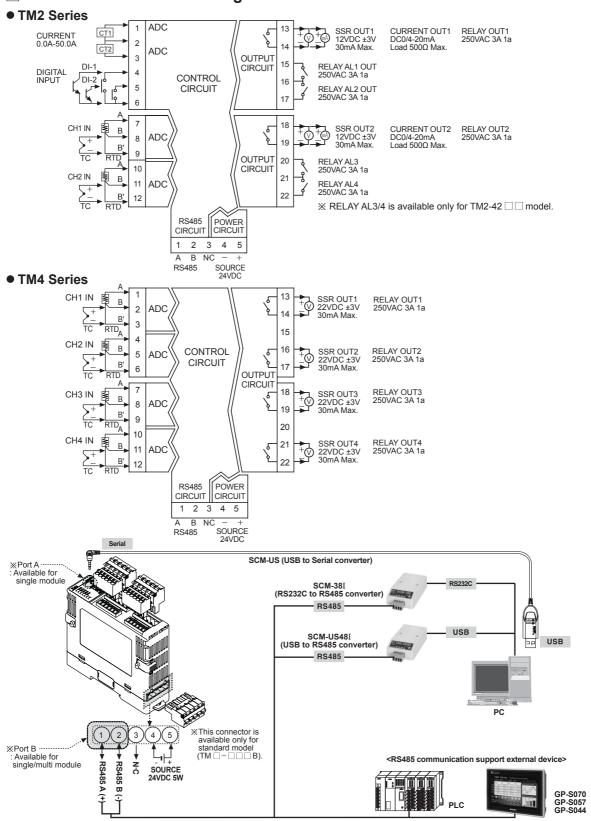
In case of thermocouple B, display accuracy cannot be ensured under 400°C.

In case of thermocouple R, S at 200°C below and thermocouple C, G, it is 3°C ±1digit Max.

<sup>%2:</sup> Applied when used out of range 23 ±5°C.

<sup>\*</sup>Environment resistance is rated at no freezing or condensation.

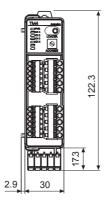
## Connections And Block Diagram

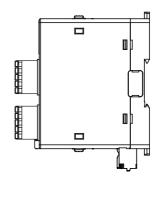


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## Dimensions

37.7 37.7 30.0 31.7 





(unit: mm) (A) Photoelectric Sensors

> (B) Fiber Optic

> > (C) Door/Area Sensors

> > (D) Proximity Sensors

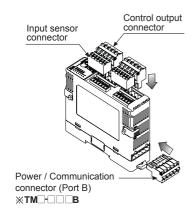
(E) Pressure

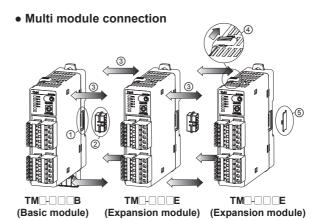
(F) Rotary Encoders

(G) Connectors Sockets

## Installation

## • Connector connection



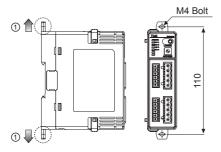


- \*① Remove END cover for both basic modules and expansion modules.
  - ② Insert expansion connectors.
  - ③ Connect an expansion module without space.
  - 4 Fix the LOCK switch by pushing it in the LOCK direction.
  - ⑤ Mount the END cover at each side.

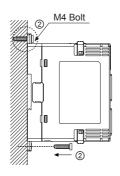
WUp to 30 expansion modules can be connected to a basic module. Use an adequate
power supply system for the power input specifications and overall capacity.

[Maximum power (155W=31ea X 5W) is required when connecting 31 units]

## Bolt Inserting



① Pull each Rail Lock switch up and down.



② Insert the bolts to fix.

(Tightening torque is 0.5N·m to 0.9N·m.)

(H) Temperature Controllers

(I) SSRs / Power Controllers

Counters

rimers

(L) Panel Meters

(M) Tacho / Speed / Pulse

(N) Display Units

(O) Sensor

(P) Switching Mode Power Supplies

(Q) Stepper Motors

(R) Graphic/ Logic Panels

(S)

Network Devices

(T) Software

Autonics H-1

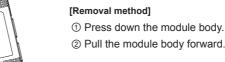
# **TM Series**

#### DIN Rail Installation

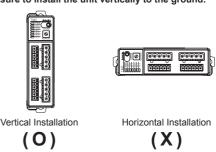
#### [Installation method]

- ① Put the top edge of the rail Lock on the top edge or the DIN rail.
- ② Push the module body in while pressing down.





\*Make sure to install the unit vertically to the ground.

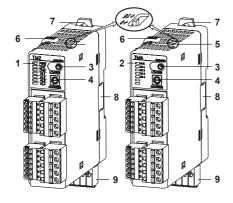


# Using END PLATE (Sold separately, Not available from Autonics), Fix firmly to attach

# Unit Description

TM2 Series

TM4 Series



#### 3. PC loader port (Port A)

Comprehensive device management program (DAQMaster, free download on our site) is for setting parameter by PC through USB to Serial converter (SCM-US, sold separately).

4. Communication address setting switch (SW1)
Used to set communication address.

Communication address group change switch (SW2)
 When communication address is over 16, select +16.

E.g.)For setting 20 address, set the communication address group change switch (SW) as +16 and set the communication address setting switch (SW1) as 4.

## 6. Lock switch

Used for fixing units to DIN rail or to the wall

#### 7. Rail Lock

Used for fixing each module when connecting module units. (up/down side)

- 8. END Cover: Remove it when connecting each module.
- 9. Power supply / communications connector (Port B)

Only Basic module TM -- 2 B

Status			Alarm output				
	Initial power on*1	Control output	N.O. Alarm occ	curred	N.C. Alarm occ	Auto tuning <sup>*2</sup>	
Display LED			OFF (OPEN)	ON (CLOSE)	OFF (CLOSE)	ON (OPEN)	
PWR LED <sup>*3</sup>	Green	Green	<b> </b> —	_	_	_	Green
CH1 LED	2400bps-Flashing	ON-RED					Flashing
CH2 LED	4800bps-Flashing	ON-RED	_	_		_	Flashing
AL1 LED	9600bps-Flashing	ON-Yellow*4	Light OFF	Light ON	Light OFF	Light ON	Light OFF
AL2 LED	19200bps-Flashing	ON-Yellow <sup>×5</sup>	Light OFF	Light ON	Light OFF	Light ON	Light OFF
AL3 LED	38400bps-Flashing	_	Light OFF	Light ON	Light OFF	Light ON	Light OFF
AL4 LED	_	_	Light OFF	Light ON	Light OFF	Light ON	Light OFF

## 2. Display LED (TM4 Series)

1. Display LED (TM2 Series)

Status Display LED		Control output	Auto tuning <sup>*2</sup>
PWR LED**3	Green	Green	Green
CH1 LED	2400bps-Flashing	ON-RED	Flashing
CH2 LED	4800bps-Flashing	ON-RED	Flashing
CH3 LED	9600bps-Flashing	ON-RED	Flashing
CH4 LED	19200bps-Flashing	ON-RED	Flashing
	38400bps-Flashing	_	_

- X1: In case of initial power on, default communication speed will be flashing for 5 sec. (1 sec. cycle).
- ※2: Each CH3 LED will be flashing during auto tuning (1 sec. cycle).
- ※3: Power LED will be flashing while communicating with external units (1 sec. cycle).
- X4: Light ON when control type for CH1 is heating & cooling type and cooling output is provided.
- X5. Light ON when control type for CH2 is heating & cooling type and cooling output is provided.

# **■ Input Sensor Type And Temperature Range**

Input sensor		No.	Dot	Display	Input range (°C)	Input range (°F)	
	K (CA)	0	1	K (CA).H	-200 to 1350	-328 to 2462	
	K (CA)	1	0.1	K (CA).L	-200.0 to 1350.0	-328.0 to 2462.0	
	1.(10)	2	1	J (IC).H	-200 to 800	-328 to 1472	
	J (IC)	3	0.1	J (IC).L	-200.0 to 800.0	-328.0 to 1472.0	
	F (CD)	4	1	E (CR).H	-200 to 800	-328.0 to 1472	
	E (CR)	5	0.1	E (CR).L	-200.0 to 800.0	-328.0 to 1472.0	
	T (CC)	6	1	T (CC).H	-200 to 400	-328 to 752	
	T (CC)	7	0.1	T (CC).L	-200.0 to 400.0	-328.0 to 752.0	
	B (PR)	8 1		B (PR)	0 to 1800	32 to 3272	
Thermocouple	R (PR)	9	1	R (PR)	0 to 1750	32 to 3182	
	S (PR)	10	1	S (PR)	0 to 1750	32 to 3182	
	N (NN)	11	1	N (NN)	-200 to 1300	-328 to 2372	
	C (TT)*1	12	1	C (TT)	0 to 2300	32 to 4172	
	G (TT) <sup>×2</sup>	13	1	G (TT)	0 to 2300	32 to 4172	
	1 (10)	14	1	L (IC).H	-200 to 900	-328 to 1652	
	L (IC)	15	0.1	L (IC).L	-200.0 to 900.0	-328.0 to 1652.0	
	11 (00)	16	1	U (CC).H	-200 to 400	-328 to 752	
	U (CC)	17	0.1	U (CC).L	-200.0 to 400.0	-328.0 to 752.0	
	Platinel II	18	1	PLII	0 to 1400	32 to 2552	
	JPt 100Ω	19 1		JPt100.H	-200 to 600	-328 to 1112	
Thermocouple  RTD	JP1 100Ω	20	0.1	JPt100.L	-200.0 to 600.0	-328.0 to 1112.0	
	DPt 100Ω	21	1	DPt100.H	-200 to 600	-328 to 1112	
	משטו זאטן	22	0.1	DPt100.L	-200.0 to 600.0	-328.0 to 1112.0	

X1: C (TT): Same as existing W5 (TT).
XDefault: K (CA).H

※2: G (TT): Same as existing W (TT).

## Error Indication

	Input sensor open error	Over temperature range
PWR LED	Red ON	
CH1 LED	RED Flashing (for 0.5 sec.)	
CH2 LED	RED Flashing (for 0.5 sec.)	
CH3 LED <sup>*1</sup>	RED Flashing (for 0.5 sec.)	
CH4 LED *1	RED Flashing (for 0.5 sec.)	
Communication output (decimal)	'31000' output	'30000 (upper limit)' output, '-30000 (lower limit)' output
Dedicated program	'OPEN' indication	'HHHH (upper limit)' indication , 'LLLL (lower limit)' indication

X1: Only for TM4 Series (4CH).

# Communication Setting

A function for external parameter setting & monitoring with PC or PLC.

## Interface

Application Standard	Compliance with EIA RS 485
Max. connection	31 units (communication address setting: 01 to 31)
Communication type	Two wire, Half Duplex
Synchronization method	Asynchronous
Communication distance	Max. 800m
Communication speed (bps)	2400, 4800, 9600 (default),19200, 38400
Communication response time	5 to 99ms
Start Bit	1bit (fixed)
Stop Bit	1bit, 2bit (default)
Parity Bit	None (default), Odd, Even
Data Bit	8bit (fixed)
Protocol	Modbus RTU

※Overlapped address setting is not allowed on the same communication line. Twisted Pair wires (for RS485 communication) must be used for communication cable.

## • Communication speed indication

Current communication speed will be flashing in case of initial power ON for 5 sec. (1 sec. cycle).



\*One module communication is allowed for Port A. Communication speed is fixed to 9600bps.

※If connects communication through Port A, Port B will be disconnected communication automatically. (A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) Door/Area Sensors (D) Proximity Sensors

(E) Pressure

(F) Rotary Encoders

(G) Connectors/

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

Timers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

Inits

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

> S) Field Network Devices

T) Software

Autonics H-15

# **TM Series**

## . Communication address setting

Set the communication address using SW1 and SW2. Setting range is 01 to 31. (XIn case setting 00, communication is not available.)

SW1	O B A G S	<b>1</b>											※Def	ault- SV	V1: 1, S	SW2: +0
SW2	0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
+0 +16	<b>∞</b> <	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
+0 +16	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31

# Sold Separately

## O Communication converter

• SCM-38I (RS232C to RS485 converter)

CE

• SCM-US48I (USB to RS485 converter)



10

• SCM-US (USB to Serial converter)

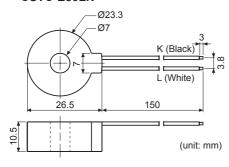


**XMax.** load current for TM Series

is 50A.

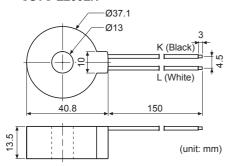
## Ourrent transformer (CT)

## • CSTC-E80LN



F=50Hz OUTPUT IN VOLTS RMS (V) Max. load current: 80A (50/60Hz) • Current ratio: 1/1000 • Wire wounded resistance: 31Ω±10% 0.001 SENSED CURRENT IN AMPS RMS (Io)

## • CSTC-E200LN



OUTPUT IN VOLTS RMS (V) • Max. load current: 200A (50/60Hz) XMax. load current for TM Series is 50A. • Current ratio: 1/1000 • Wire wounded resistance: 20Ω±10% 0.01

0.001 0.1 SENSED CURRENT IN AMPS RMS (Io)

XDo not supply primary current in case that CT output is open. High voltage will be generated in CT output. \*\*The current for above two CTs is 50A same but inner hole sizes are different. Please use this your environment.

H-16 **Autonics** 

## Proper Usage

## O Simple failure diagnosis

- When display LED is flashing every 0.5 sec. or when error message is indicated on external units
  - It represents input sensor open error. Cut off the power of controller and check input sensor connection.

If sensor is properly connected, disconnect sensor line from the controller and short the input terminal (+) / (-). Then, make sure that current indoor temperature is indicated. If current indoor temperature is properly indicated, it represents no errors detected. If external unit displays 'HHHH' or 'LLLL', please contact our A/S center.

(Current indoor temperature checking is available only if selecting thermocouple type.)

· Make sure proper input sensors are selected.

#### . When no output is operated

 Check output display LED at the front. In case output display LED does not work properly, please check each parameter setting again. In case output display LED works properly, disconnect the output terminal and check controller's output type (Relay contact, SSR, Current) again.

# When external units receive no response or error data

- · Check communication converter first.
- Do not install the unit with overlapping communication converter lines and AC power supply lines.
- Use separate power supply (24VDC) for communication converter if possible.
- Strong external noise could be a possible cause for this symptom. Please contact our A/S center. In addition, analyze the main cause that triggers strong noise and take measures to prevent it. Even though this unit complies with proper noise resistance standards, consistent noise induction could affect internal circuit break.

### When communication does not work properly

- · Check converter's power supply and connection.
- · Check communication setting.
- Check main body's connections to external units.

## O Caution during use

- Use DC power only.
- Keep the ambient temperature -10°C to 50°C.
- For more accurate controlling, start temperature controlling approx. 20 minutes later after connecting input sensors and supplying power.
- In case display accuracy does not meet the specification, check Input Bias parameter first.
- Power switch or a circuit breaker must be installed for proper application.
- Make sure that the power switch or a circuit breaker installed near operators.
- This unit is solely allowed for temperature controlling application. Do not apply this unit as a voltage meter or current meter.
- When line extension is required, please use specified compensation line. If not, there occurs temperature difference at the joint part between thermocouples and extension lines.
- In case of using RTD, line connection must be done with 3 wires. When line extension is required, use the same wire with material, thickness and length. Different line resistance may cause temperature difference.
- Make sure controller's line connection must be separated from high voltage line or power supply line in order to prevent induced noise.
- If it is required that power supply line should be connected near input signal line, use line filter on controller's power supply line and input signal line must be shielded.
- Avoid installing controllers adjacent to high frequency noise generating units including high frequency soldering machine, high frequency sewing machine, and high capacity SCR controllers and motors.
- Avoid using the unit near radio, TV or wireless machines that may cause high frequency interference.
- When changing input sensors, power off the controller first. Connect input sensors as specified and supply the power again. Then, change & download related parameters using PC loader program.
- Use (-) driver screws (2mm) or use plastic driver screws. If not, it might cause product damage.
- Twist Pair wires must be used for communication cable.
   Connect Ferrite Bead at each end of line in order to reduce the effect of external noise.
- Avoid installing the unit with overlapping communication line and AC power line together.
- Draw a draft while using the controllers. In case of installing at a closed area, please take measures for ventilation.
- This unit may be used in the following environments.
  - Indoor
  - Altitude: Under 2,000mPollution degree 2Installation category II

(A) Photoelectric Sensors

(B) Fiber Optic

(C) Door/Area Sensors

(D) Proximity Sensors (E)

(F) Rotary

(G) Connectors/ Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

imers

Panel Meters

(M) Tacho / Speed / Pulse Meters (N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers

(R) Graphic/ Logic Panels

(S) Field Network Devices

T) Software

Autonics H-17